

Contrast Feature Dependency Pattern Mining for Controlled Experiments with Application to Driving Behavior

Qingzhe Li, Liang Zhao, Yi-Ching Lee, Yanfang Ye, Jessica Lin, Lingfei Wu

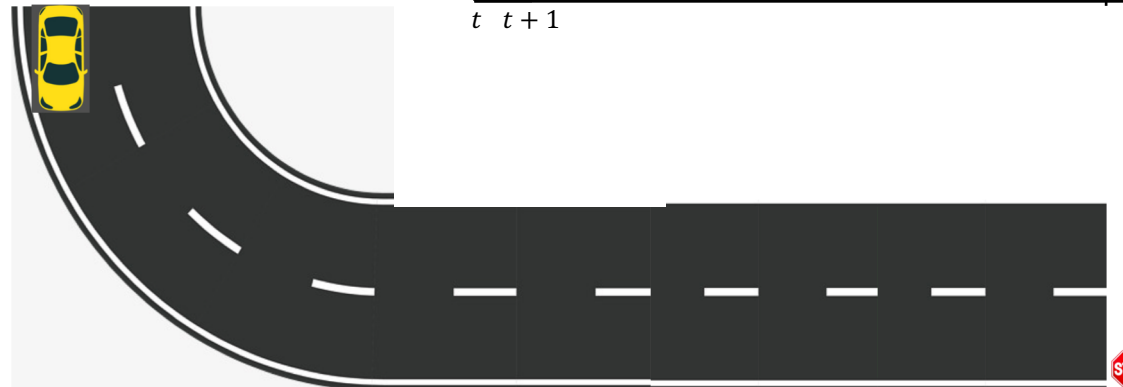
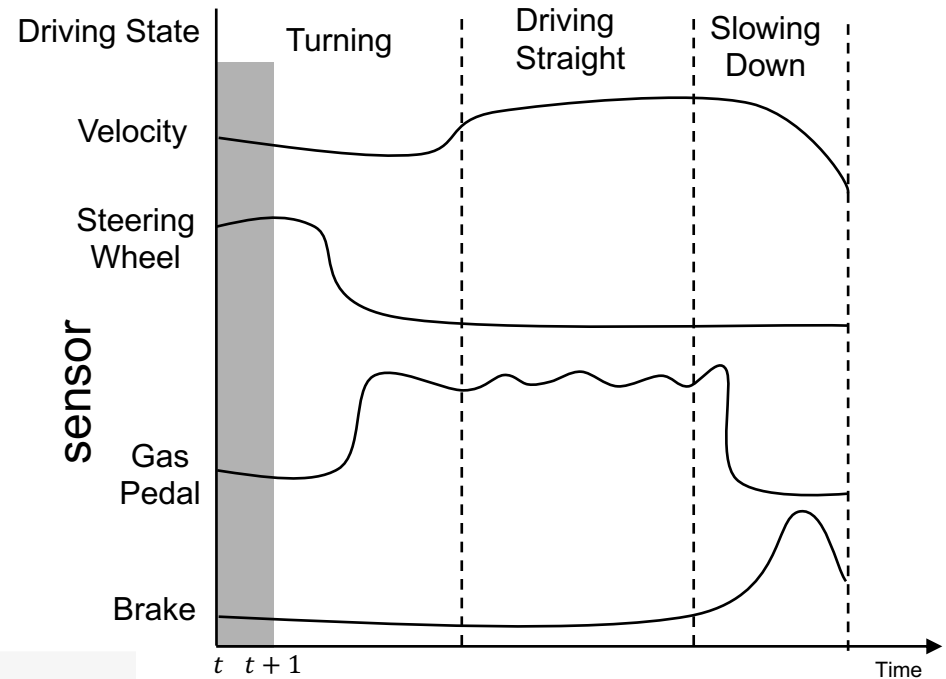
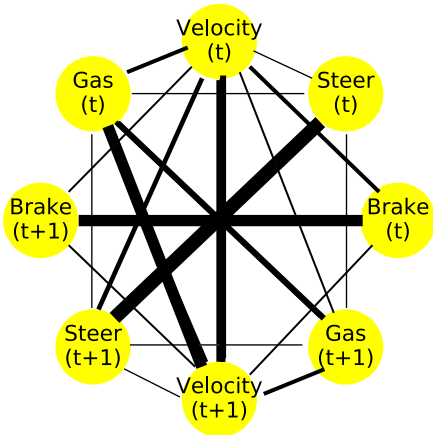
Presented by Qingzhe Li



Introduction

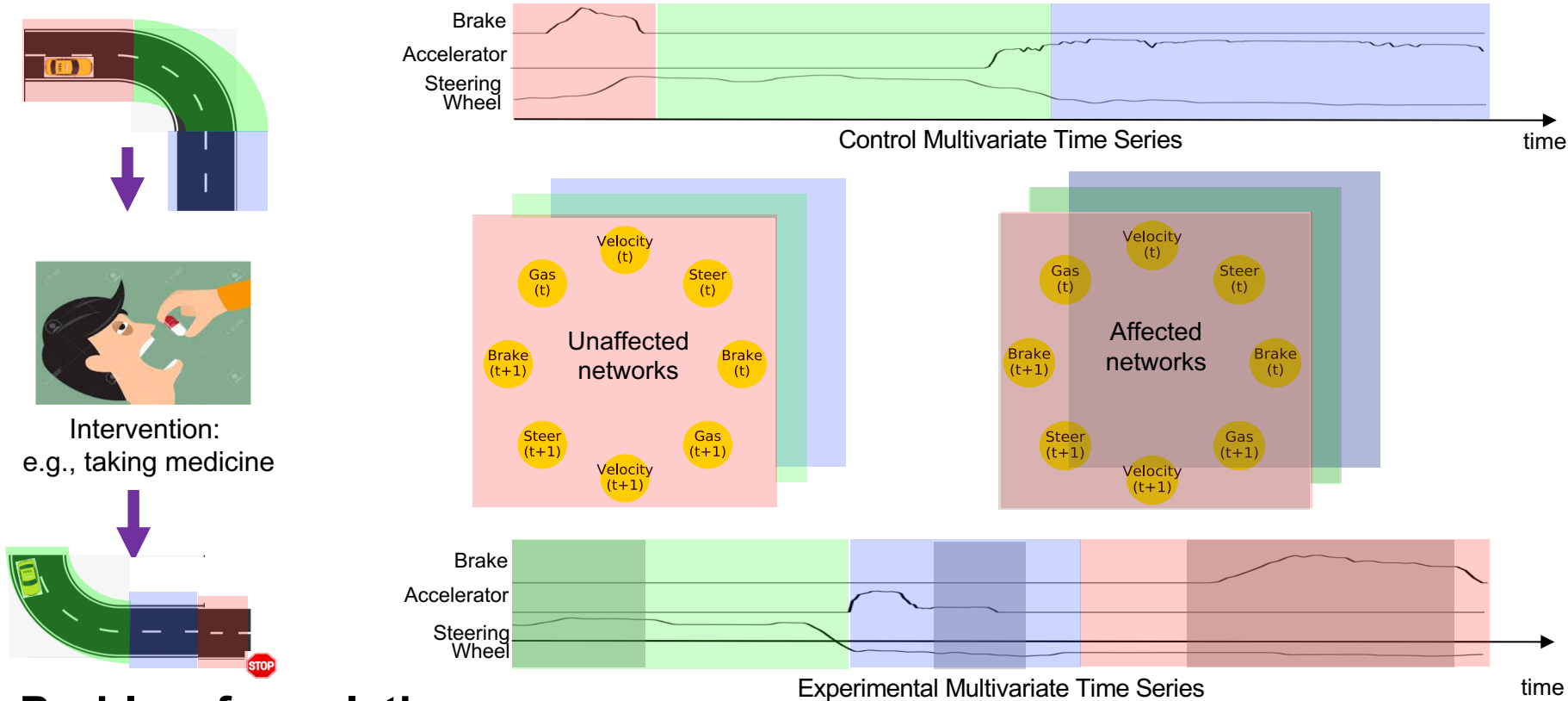
- Characterizing the latent state in multivariate time series

Dependency Network of Driving State



Contrast Pattern in Controlled Experiments

- **Goal: determine which the driving behaviors are affected or not**



- **Problem formulation**

Inputs: 1. Control Multivariate Time Series 2. Experimental Multivariate Time Series

Outputs: 1. Latent state assignments 2. Contrast pattern detection 3. Contrast pattern characterization

Challenges

1. Integrally modeling the coupled outputs:

Outputs: 1. Latent state assignments 2. Contrast pattern detection 3. Contrast pattern characterization

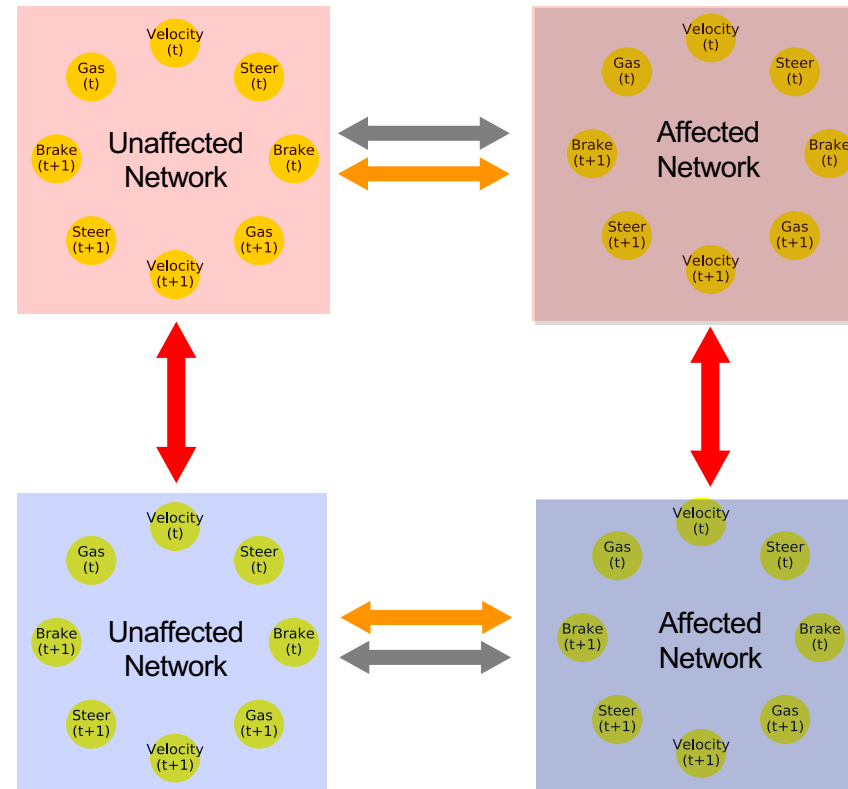
Coupled

2. Differentiating the dependency networks:

↔ Similarities caused by same latent state

↔ Differences caused by intervention

↔ Differences caused by latent state



Resolving Challenge 1

Input:

1. Control MTS: X
2. Experimental MTS: \hat{X}

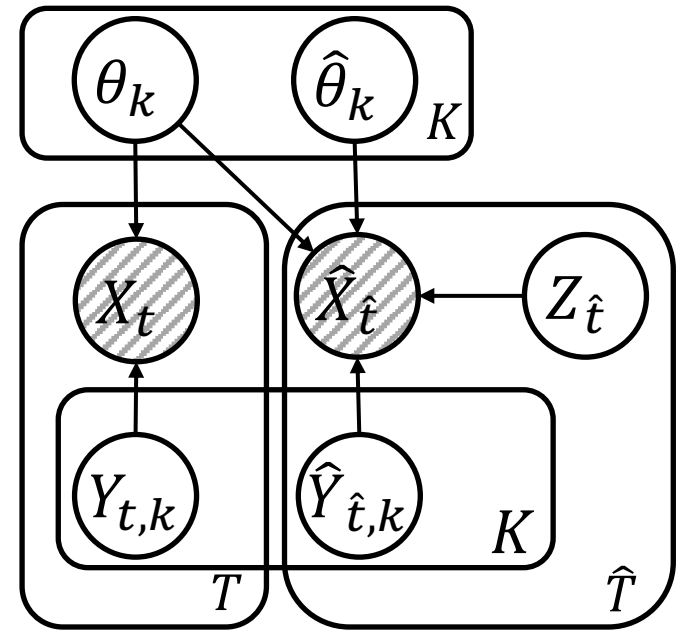
Coupled

Output:

1. Latent state assignments: Y, \hat{Y}
2. Contrast pattern detection: Z
3. Contrast latent state characterization: $\theta = \{\theta_k\}_{k=1}^K, \hat{\theta} = \{\hat{\theta}_k\}_{k=1}^K$

- Proposing an integrated generative model for contrast pattern mining problem
- Joint likelihood

$$p(X, \hat{X} | Y, Z, \theta, \hat{\theta}) = p(X | Y, \theta) \cdot p(\hat{X} | \hat{Y}, Z, \theta, \hat{\theta})$$



Resolving Challenge 2

- **Intuitions / Motivations**

- The latent states are decided by environments
- The contrast patterns are decided by intervention
- The intervention is unlikely to change the latent states, i.e., $Similarity(\theta_i, \hat{\theta}_i) > Similarity(\theta_i, \theta_j)$

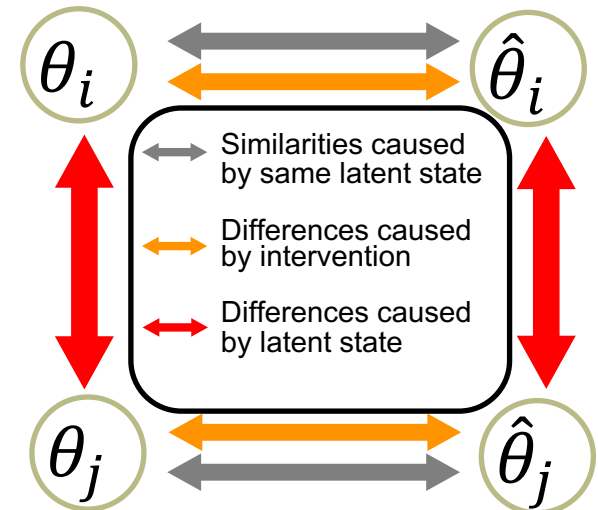
- **Technical challenge**

- Flawed definition of similarity directly between two inverse covariance matrices, for example:
 - Non-interpretable single element in θ_i
 - Different scales between θ_i and θ_j

- **Proposing Partial Correlation Based Regularization**

$$\mathcal{R}_C(\theta, \hat{\theta}) = \lambda \cdot \sum_k^K \|\rho_k - \hat{\rho}_k\|_F^2$$

where ρ_k and $\hat{\rho}_k$ are the partial correlation matrices computed from θ_i and $\hat{\theta}_k$



Overall Objective Function

Objective:

Loss function: negative log likelihood

Partial Correlation Based Regularization

$$\arg \min_{\theta, \hat{\theta}, Y, \hat{Y}, Z} \mathcal{L}(Y, \hat{Y}, Z, \theta, \hat{\theta}) + \mathcal{R}_C(\theta, \hat{\theta}) + \mathcal{R}_T(Y, \hat{Y}, Z)$$

Smoothing the latent state assignments between the neighbor time indices

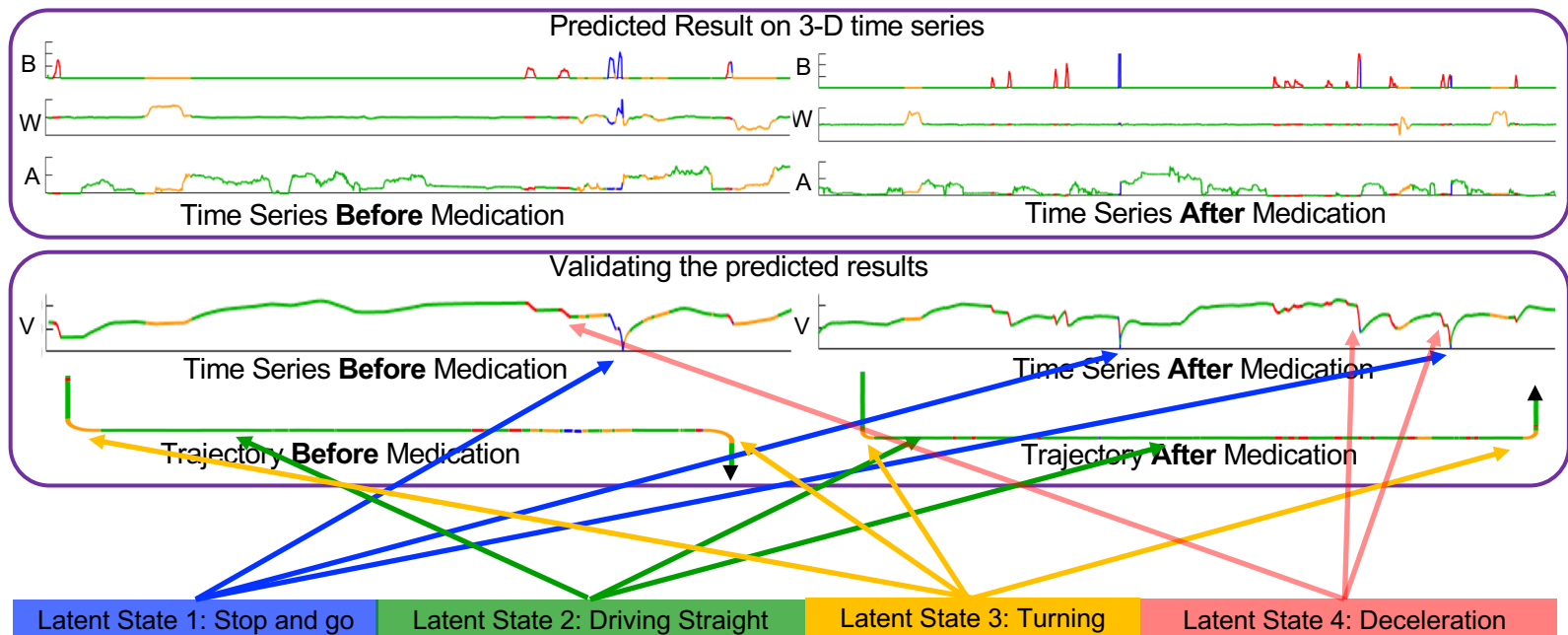
$$\text{where } \mathcal{R}_T(Y, \hat{Y}, Z) = \sum_{t=2}^T \gamma \mathbf{1}(Y_t \neq Y_{t-1}) + \sum_{\hat{t}=2}^{\hat{T}} \beta \mathbf{1}(Z_{\hat{t}} \neq Z_{\hat{t}-1}) + \gamma \mathbf{1}(\hat{Y}_{\hat{t}} \neq \hat{Y}_{\hat{t}-1})$$

Optimization Algorithm:

- Repeat
 - Expectation-step: fix continuous variables $(\theta, \hat{\theta})$ optimize discrete variables (Y, Z)
 - By formulating a dynamic programming problem
 - Maximization-step: fix Y, Z optimize $\theta, \hat{\theta}$
 - By developing an ADMM based algorithm
- Until Stationarity

Experimental Result on Real-world Datasets

- Predicted Latent State Assignments



Experimental Result on Real-world Datasets (cont.)

- Visualizing the learned contrast patterns

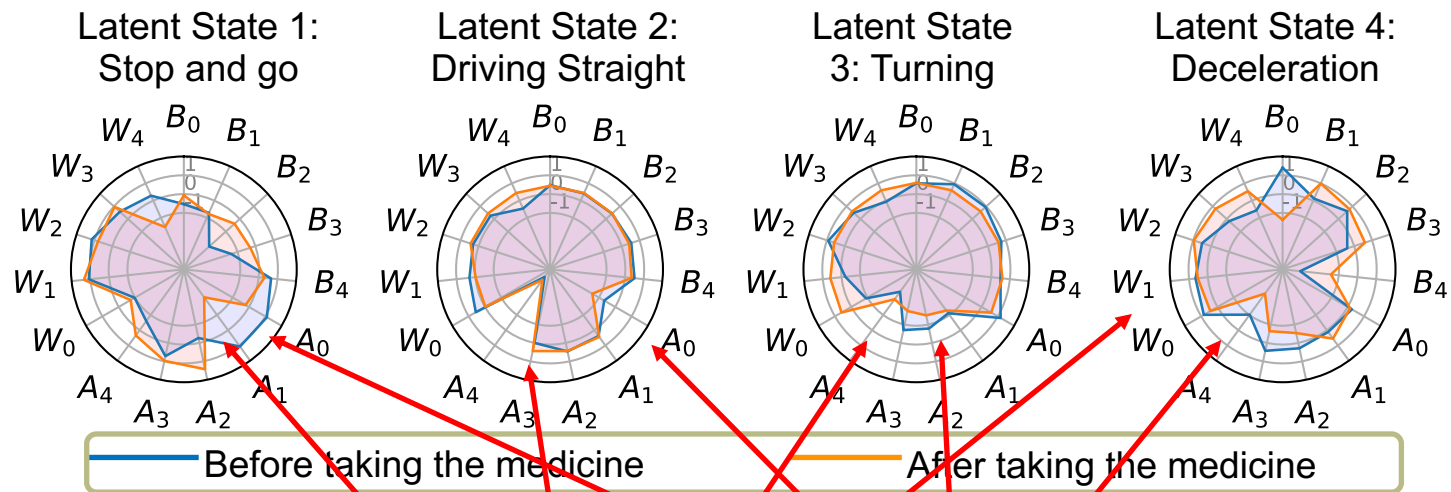


Figure: Closeness centrality scores of the learned dependency networks. The higher score of the node, the more important of the node in the network

The non-overlapped areas indicate the driving behaviors have been changed by the medicine.

For the same latent state, the centrality scores are similar of all nodes

QUESTIONS?



Experimental Result on Synthetic Datasets

TABLE II: The (macro) F_1 scores of predicted Y, \hat{Y} , and Z assignments

Method	Dataset 1			Dataset 2			Dataset 3		
	Y	\hat{Y}	Z	Y	\hat{Y}	Z	Y	\hat{Y}	Z
K-means+1SVM	0.50	0.51	0.58	0.33	0.34	0.61	0.28	0.27	0.60
K-means+EE	0.50	0.51	0.23	0.33	0.34	0.25	0.28	0.27	0.25
K-means+IF	0.50	0.51	0.23	0.33	0.34	0.26	0.28	0.27	0.26
K-means+LOF	0.50	0.51	0.15	0.33	0.34	0.18	0.28	0.27	0.21
K-shape+1SVM	0.51	0.51	0.54	0.34	0.33	0.56	0.26	0.24	0.55
K-shape+EE	0.51	0.51	0.23	0.34	0.33	0.25	0.26	0.24	0.25
K-shape+IF	0.51	0.51	0.24	0.34	0.33	0.26	0.26	0.24	0.25
K-shape+LOF	0.51	0.51	0.14	0.34	0.33	0.19	0.26	0.24	0.21
TICC+1SVM	0.99	0.72	0.47	0.29	0.24	0.48	0.25	0.23	0.51
TICC+EE	<u>0.99</u>	0.72	0.35	0.29	0.24	0.25	0.25	0.23	0.25
TICC+IF	0.99	0.72	0.29	0.29	0.24	0.27	0.25	0.23	0.25
TICC+LOF	0.99	0.72	0.30	0.29	0.24	0.20	0.25	0.23	0.25
GMM+1SVM	0.95	0.87	0.49	0.85	0.80	0.50	0.83	0.78	0.52
GMM+EE	0.95	0.87	0.22	0.85	<u>0.80</u>	0.22	0.83	0.78	0.24
GMM+IF	0.95	0.87	0.23	0.85	0.80	0.24	0.83	0.78	0.25
GMM+LOF	0.95	0.87	0.16	0.85	0.80	0.18	0.83	0.78	0.21
Baseline ($\lambda = 0$)	0.94	0.92	0.89	0.86	0.63	0.88	0.83	0.59	0.76
CPM-P (ours)	0.99	0.99	0.98	0.99	0.75	0.89	0.99	0.99	0.98

Only use loss function without proposed regularization outperform comparison

Our method successfully identified the latent states and the contrast patterns with high F_1 score

Method without considering the coupling between the latent state and contrast patterns does NOT work